

Local recognition of the point graphs of some Lie incidence geometries

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Abstract

Given a finite Lie incidence geometry which is either a polar space of rank at least 3 or a strong parapolar space of symplectic rank at least 4 and diameter at most 4, or the parapolar space arising from the line Grassmannian of a projective space of dimension at least 4, we show that its point graph is determined by its local structure. This follows from a more general result which classifies graphs whose local structure can vary over all local structures of the point graphs of the aforementioned geometries. In particular, this characterises the strongly regular graphs arising from the line Grassmannian of a finite projective space, from the half spin geometry related to the quadric $Q^+(10, q)$ and from the exceptional group of type $E_6(q)$ by their local structure.

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1 Introduction

Let, with standard notation, $\Gamma = (V, \sim)$ be a graph and for each $v \in V$, let $\Gamma(v)$ be the *local graph at v* , that is, the graph induced on the neighbours of v . We say that a graph Γ is locally isomorphic to a graph Γ' if the set of local graphs $\{\Gamma(v) \mid v \in V\}$ is a subset of $\{\Gamma'(v') \mid v' \in V'\}$ (identifying isomorphism types). If all local graphs in Γ' are isomorphic, then one wishes to conclude that each connected locally isomorphic graph is (globally) isomorphic. In this case, we say that Γ is determined by its local structure. Call a graph Γ *locally Λ* if all $\Gamma(v)$ are isomorphic to Λ . For a graph Γ locally Λ , it seems fair to say that the larger the diameter of Γ , the less likely it is that it is unique as being locally Λ , since in this case it is more likely that nontrivial quotients exist. In particular, Weetman [25] shows that if Λ is a finite graph of girth at least six, then there exists an infinite graph Γ which is locally Λ .

Nevertheless, for many choices of Λ all graphs Γ which are locally Λ have been classified. For instance, Hall shows that there are precisely three graphs which are locally Petersen [16]. More generally, for at least the following Λ a classification or at least a partial classification is known

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31 (ordered by the date of publication): graphs which are locally polar of order 2 [11], locally co-
32 triangular graphs [19], locally icosahedral graphs [4], locally Λ graphs for small Λ [17], locally
33 Kneser graphs [18], locally 4-by-4 grid graphs [2], locally Petersen or $K_{3,3}$ -graphs [3], locally
34 Paley graphs [7], locally co-Heawood graphs [8]. Weetman [26] and Brouwer [6] show that Γ
35 has finite diameter if it is locally Λ for many choices in which Λ is strongly regular. In partic-
36 ular, for such Λ there is a finite list of graphs for which Γ is locally Λ . The characterisation by
37 local graphs is also crucial in the characterisation of distance-regular graphs, for instance see
38 Corollary 5.6 in [20] in case of the characterisation of certain Grassmann graphs, or also [21].
39 Here it is usually assumed that Γ is distance-regular.

40 In the present paper, we deal with local characterisations of distance regular graphs arising
41 from spherical buildings by taking one type of vertices of the building as the vertices of our
42 graph, adjacent when contained in adjacent chambers. These graphs are the point graphs of
43 the corresponding so-called *Lie incidence geometries*, that is, incidence geometries arising from
44 spherical buildings in a well-defined way. The idea is to use some local characterisation of
45 the underlying geometries. In order to do so, we must overcome two difficulties: (1) We must
46 define the lines of the geometry from the given graph and the local data; (2) Since most local
47 geometric characterisations use the framework of the (strong) parapolar spaces, we must show
48 that the obtained point-line geometry is a parapolar space. The case where we start with the
49 point graph of a polar space has to be considered separately and shall be done using the axiom
50 system of Buekenhout & Shult [10].

51 With the notation that we shall introduce in Section 2, the following general local recognition
52 theorem is a main consequence of our results.

53 **Main Result 1.1.** *Let Δ be a finite Lie incidence geometry, which is either a strong parapolar space*
54 *with symplectic rank at least 4 and diameter at most 4, or the parapolar space arising from the line*
55 *Grassmannian of a projective space of dimension at least 4, or a polar space with rank at least 3. Then*
56 *the point graph of Δ is, as a connected graph, completely determined by its local structure.*

57 This will be a consequence of the more detailed Main Results 2.1 and 2.2, which we will state
58 after introducing some preliminaries in the next section. The other sections are then devoted
59 to the proofs of these main results.

60 Main Result 1.1 implies that the following strongly regular graphs are determined by their
61 local structure: the graphs on the lines of (finite) projective spaces (adjacent when non-disjoint),
62 the point graphs of polar spaces, the graph on half of the maximal singular subspaces of the
63 hyperbolic quadric $Q^+(10, q)$ (adjacent when intersecting in a plane) and the $E_{6,1}(q)$ graph
64 (with notation and terminology of [9]).

65 The case of being locally isomorphic to the line Grassmannian of a projective space of dimen-
66 sion at least 4 is also covered by Corollary 5.6 of [20], although under the additional assumption
67 that Γ is strongly regular and has the right parameters.

68 2 Preliminaries

69 The main players in this paper are some Lie incidence geometries arising from spherical build-
70 ings. Since these are point-line geometries, we first introduce some terminology concerning
71 these.

72 2.1 Point-line geometries

73 A *point-line geometry* is a pair $\Delta = (X, \mathcal{L})$ with X a set and \mathcal{L} a set of subsets of \mathcal{P} . The
 74 elements of X are called *points*, the members of \mathcal{L} are called *lines*. If $p \in X$ and $L \in \mathcal{L}$ with
 75 $p \in L$, we say that the point p *lies on* the line L , and the line L *contains* the point p , or *goes*
 76 *through* p . If two (not necessarily distinct) points p and q are contained in a common line, they
 77 are called *collinear*, denoted $p \perp q$ (since we will always deal with geometries in which each
 78 point lies on at least one line, we always have $p \perp p$, for each $p \in X$). If they are not contained
 79 in a common line, we say that they are *noncollinear*. For any point p and any subset $P \subset \mathcal{P}$, we
 80 denote

$$p^\perp := \{q \in \mathcal{P} \mid q \perp p\} \text{ and } P^\perp := \bigcap_{p \in P} p^\perp.$$

81 A *partial linear space* is a point-line geometry in which every line contains at least three points,
 82 and where there is a unique line through every pair of distinct collinear points p and q . That
 83 line is then denoted with pq . A point-line geometry is *degenerate* if there is some point collinear
 84 to each point.

85 Let $\Delta = (X, \mathcal{L})$ be a partial linear space. A subset $S \subseteq X$ is called a *subspace* of Δ when every
 86 line L of \mathcal{L} that contains at least two points of S , is contained in S . A subspace S in which all
 87 points are mutually collinear, or equivalently, for which $S \subseteq S^\perp$, is called a *singular* subspace.
 88 If S is moreover not contained in any other singular subspace, it is called a *maximal* singular
 89 subspace.

90 We now take a look at two specific classes of point-line geometries: the polar and the parapolar
 91 spaces.

92 2.2 Polar and parapolar spaces

93 Concerning polar spaces, we take the viewpoint of Buekenhout–Shult [10]. Since it suffices in
 94 this paper to consider polar spaces of finite rank and which are not degenerate, we include this
 95 in our definition.

96 A *gamma space* is a point-line geometry $\Delta = (X, \mathcal{L})$ such that for each line $L \in \mathcal{L}$ and each
 97 point $p \in X$, either no, or exactly one, or all points of L are collinear to p .

98 A *Shult space* is a point-line geometry $\Delta = (X, \mathcal{L})$ such that for each line $L \in \mathcal{L}$ and each point
 99 $p \in X$, either exactly one, or all points of L are collinear to p .

100 A *polar space (of rank r)*, $2 \leq r \in \mathbb{N}$, is a Shult space that is not degenerate and for which the
 101 maximal singular subspaces are projective spaces of dimension $r - 1$.

102 Concerning parapolar spaces, we take the viewpoint of Cooperstein [13], as explained in Chap-
 103 ter 13 of [23]. Again, it suffices to consider parapolar spaces of finite symplectic rank. The
 104 following definition is motivated by Lemma 13.4.2 of [23].

105 A parapolar space of symplectic rank at least r (resp. uniform symplectic rank r), $3 \leq r \in \mathbb{N}$,
 106 is a gamma space $\Delta = (X, \mathcal{L})$ such that for each pair of distinct non-collinear points $x, y \in X$,
 107 the geometry with point set $x^\perp \cap y^\perp$ and set of lines all members of \mathcal{L} completely contained
 108 in $x^\perp \cap y^\perp$ is either empty, a single point, or a polar space of rank at least $r - 1$ (resp. exactly
 109 rank $r - 1$), and such that for every line $L \in \mathcal{L}$, the set L^\perp contains at least two non-collinear
 110 points.

111 Let $\Delta = (X, \mathcal{L})$ be a parapolar space of symplectic rank at least 3. By Lemma 13.4.1(2) of [23],
 112 the singular subspaces of Δ are projective spaces. For $x \in X$, the *point residual (at x)* is the

113 point-line geometry with point set the set of all lines of Δ through x and with as set of lines the
 114 line pencils with vertex x in some singular subspace of Δ isomorphic to a projective plane.

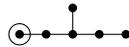
115 Our definition of parapolar spaces does not exclude the possibility of being a polar space. A
 116 parapolar space $\Delta = (X, \mathcal{L})$ shall be called *proper* when it is not a polar space, that is, when
 117 there exist a point $p \in X$ and a line $L \in \mathcal{L}$ no point of which is collinear to p .

118 2.3 Lie incidence geometries

119 We now sketch how Lie incidence geometries arise, deferring to the literature for the precise
 120 definition of the concept of a spherical building (see for instance [1, 24]). As in the latter ref-
 121 erence, we view a spherical building as a numbered simplicial chamber complex, that is, a
 122 simplicial complex with a type function on the set of vertices such that each chamber (which
 123 is a maximal simplex) contains precisely one vertex of each type. Let i be a type of a building
 124 of type X_n , where X_n is a connected spherical Coxeter diagram. A simplex obtained from a
 125 chamber by deleting the vertex of type i is called an *i-panel*. Let X be the set of vertices of type
 126 i and let \mathcal{L} be the set of subsets of X with generic member the set of vertices of type i forming
 127 a chamber together with a fixed i -panel. Then $\Delta = (X, \mathcal{L})$ is a point-line geometry, called the
 128 *i-Grassmannian* of the corresponding spherical building, and a *Lie incidence geometry of type $X_{n,i}$* .

129 If the diagram X_n is simply laced and the building is finite, then the building is defined over a
 130 unique finite field \mathbb{F}_q , for some prime power q and we denote the corresponding Lie incidence
 131 geometries by $X_{n,i}(q)$. The Lie incidence geometries of type $B_{n,1}$ are polar spaces and we will
 132 not need a special notation for them depending on the diagram. We just remark that the po-
 133 lar spaces $D_{n,1}$ are the point-line geometries arising from non-degenerate hyperbolic quadrics
 134 $Q^+(2n - 1, q)$ in the projective space $\text{PG}(2n - 1, q)$ (using standard notation), and that the
 135 corresponding so-called half spin geometries $HS(2n - 1, q)$ are the Lie incidence geometries
 136 $D_{n,n}(q)$.

137 A Lie incidence geometry of type $X_{n,i}$ is often represented by encircling the node of type i in
 138 the Coxeter diagram X_n . This representation has the advantage of making the dimensions of
 139 the maximal singular subspaces apparent: they are equal to the lengths of the longest linear
 140 subdiagrams where the encircled node is an initial node. For instance, the maximal singular
 141 subspaces of a Lie incidence geometry of type E_6 , have dimensions 4 and 5, as is apparent from
 142 the diagram



143 by deleting either the upper vertex, or the two vertices at the right.

144 2.4 Restatement of the Main Result

145 Denoting the point graph of a Lie incidence geometry $X_{n,i}(q)$ by $\Gamma(X_{n,i}(q))$, $n \in \mathbb{N}$, $i \in$
 146 $\{1, 2, \dots, n\}$, q a prime power and X_n a simply laced spherical Dynkin diagram, Main Re-
 147 sult 1.1 follows from the following more general (concerning hypotheses) and at the same time
 148 more specific (enumerating all concrete possibilities) results.

149 **Main Result 2.1.** *Let Γ' be the disjoint union of the point graphs of all finite polar spaces of rank at*
 150 *least 3. Then any connected graph Γ locally isomorphic to Γ' is the point graph of a finite polar space of*
 151 *rank at least 3.*

152 Note that we do not even require that different connected components of Γ' in Main Result 2.1
 153 are defined over the same finite field, nor do we assume that the graph Γ is finite.

154 For parapolar spaces, there is an explicit list [22] of Lie incidence geometries that are strong
 155 parapolar spaces of symplectic rank at least 4 and diameter at most 4, or of symplectic rank 3
 156 and diameter 2. This allows of the following statement.

157 **Main Result 2.2.** *Let Γ be a connected graph locally isomorphic to the disjoint union of $\Gamma(A_{n,2}(q))$,
 158 $n \geq 4$, q ranging over all prime powers, $\Gamma(D_{n,n}(q))$, $5 \leq n \leq 9$, q ranging over all prime powers,
 159 $\Gamma(E_{6,1}(q))$, q again ranging over all prime powers, and $\Gamma(E_{7,7}(q))$, q once again ranging over all prime
 160 powers. Then Γ is isomorphic to either $\Gamma(A_{n,2}(q))$, $n \geq 4$, $\Gamma(D_{n,n}(q))$, $5 \leq n \leq 9$, $\Gamma(E_{6,1}(q))$, or
 161 $\Gamma(E_{7,7}(q))$, for some prime power q .*

162 Note that, for any prime power q , $\Gamma(A_{n,2}(q))$, $n \geq 4$, $\Gamma(D_{5,5}(q))$ and $\Gamma(E_{6,1}(q))$ are strongly
 163 regular (hence have diameter 2), whereas $\Gamma(D_{6,6}(q))$, $\Gamma(D_{7,7}(q))$ and $\Gamma(E_{7,7}(q))$ have diameter 3,
 164 and $\Gamma(D_{8,8}(q))$ and $\Gamma(D_{9,9}(q))$ have diameter 4.

165 Since the vertices of the graphs we will consider are the points of a Lie incidence geometry, we
 166 will from now on deviate from standard notation and denote the vertex set of a graph by X .

167 3 Proof of Main Result 2.1 and most of Main Result 2.2

168 Let $\Gamma = (X, \sim)$ be a graph and q a natural number. The q -clique extension $q\Gamma$ of Γ is the graph
 169 with vertices $t_i(x)$, $i \in \{1, 2, \dots, q\}$, $x \in X$, with $t_i(x)$ and $t_j(y)$ adjacent if either $x = y$ and
 170 $i \neq j$, or $x \sim y$. If the set of vertices equal or adjacent to a vertex $x \in X$ coincides with the set
 171 of vertices equal or adjacent to $y \in X$, then the sets $\{t_i(x) \mid i = 1, 2, \dots, q\}$ and $\{t_i(y) \mid i =$
 172 $1, 2, \dots, q\}$ cannot be distinguished in $q\Gamma$ (in fact, in their union, every vertex plays the same
 173 role). However, this is the only obstruction, as we will show below. For an arbitrary set S of
 174 vertices, we denote by S^\perp the set of vertices equal or adjacent to every vertex in S . For $S = \{x\}$,
 175 we denote $S^\perp = x^\perp$.

176 **Lemma 3.1.** *Let $\Gamma = (X, \sim)$ be a graph and let q be a natural number. Suppose $x \in X$ has the property
 177 that the set $(x^\perp)^\perp$ coincides with $\{x\}$. Then in $q\Gamma$, we have $\{t_i(x) \mid i = 1, 2, \dots, q\} = (t_j(x)^\perp)^\perp$, for
 178 each $j \in \{1, 2, \dots, q\}$.*

179 *Proof.* This follows immediately from the definition of $q\Gamma$. □

180 Under the assumptions of Lemma 3.1, we call the set $\{t_i(x) \mid i = 1, 2, \dots, q\}$ a *ray*, or *the ray of*
 181 x , and we say that the ray is *reconstructable*. Also, the natural number q is called the *height* of
 182 the graph and is well defined under the assumptions of Lemma 3.1.

183 Since each vertex of the point graph of a polar space has the property mentioned in Lemma 3.1,
 184 each point of the point graph of any Lie incidence geometry which is a (proper) parapolar space
 185 also has that property.

186 Now let $\Gamma = (X, \sim)$ be a connected graph which has at each of its vertices the local structure of
 187 the q -clique extension of the point graph of a Lie incidence geometry which is either a parapolar
 188 space of symplectic rank at least 3 and diameter 2 in which the lines carry $q + 1$ points, or
 189 a polar space of rank at least 2 in which the lines carry exactly $q + 1$ points (also q depends on
 190 the vertex). This Lie incidence geometry is called the *local geometry at the corresponding vertex*
 191 and denoted $\Delta(x)$; hence $\Gamma(x) \cong q\Delta(x)$. Let $p \in X$ be an arbitrary vertex of Γ and let $x \sim p$;

192 so $x \in \Gamma(p)$. Then, by our observation, the rays of the local graph $\Gamma(p)$ are reconstructable.
 193 The ray R_x to which x belongs is equal to $(x^{\perp p})^{\perp p}$, where \perp_p denotes adjacency in $\Gamma(p)$. Hence
 194 $x^{\perp p} = (x^{\perp} \cap p^{\perp}) \setminus \{p\}$ and so $R_x = (((x^{\perp} \cap p^{\perp}) \setminus \{p\})^{\perp} \cap p^{\perp}) \setminus \{p\}$. Then

$$R := R_x \cup \{p\} = ((x^{\perp} \cap p^{\perp}) \setminus \{p\})^{\perp} \cap p^{\perp} = (x^{\perp} \cap p^{\perp})^{\perp}.$$

195 Now note that the latter is symmetric in x and p , hence the ray in $\Gamma(x)$ to which p belongs is
 196 equal to $R \setminus \{x\}$. Since R_x is determined in $\Gamma(p)$ by any of its members y , we now deduce that
 197 R is determined by any pair (p_1, p_2) of its points as $p_1 \cup R_{p_2}$, with R_{p_2} the ray in $\Gamma(p_1)$ to which
 198 p_2 belongs. We denote the set R by $R[p_1, p_2]$ and call it an *extended ray*. This already has, by
 199 connectivity, the following consequence.

200 **Lemma 3.2.** *The heights of the local graphs at two distinct vertices of Γ coincide.*

201 We now define the set \mathcal{L} as the set of all extended rays $R[p_1, p_2]$, with $p_1 \sim p_2$, for $p_1, p_2 \in X$
 202 and we define the geometry $\Delta = (X, \mathcal{L})$. Clearly, the point graph of Δ is Γ . Also, the fact that
 203 lines are determined by any pair of their points translates in the property that Δ is a partial
 204 linear space.

205 **Lemma 3.3.** *The geometry $\Delta = (X, \mathcal{L})$ is a gamma space.*

206 *Proof.* Let $p, x, y \in X$, with $p \sim x \sim y \sim p$ and $R[p, x] \neq R[p, y]$. Note that the rays in $\Gamma(p)$
 207 correspond to the points of $\Delta(p)$. Since in $\Delta(p)$ the line through two collinear points u, v is
 208 given by $(u^{\perp} \cap v^{\perp})^{\perp}$ (with \perp the usual collinearity relation including equality), in $\Gamma(p)$, the
 209 union U of the rays corresponding to the line of $\Delta(p)$ through the points $R[p, x] \setminus \{p\}$ and
 210 $R[p, y] \setminus \{p\}$ is given by

$$U = (((x^{\perp} \cap y^{\perp} \cap p^{\perp}) \setminus \{p\})^{\perp} \cap p^{\perp}) \setminus \{p\},$$

211 which, as above, equals

$$(x^{\perp} \cap y^{\perp} \cap p^{\perp})^{\perp} \setminus \{p\}.$$

212 Since $R[x, y]$ does not contain p and since

$$(x^{\perp} \cap y^{\perp})^{\perp} \subseteq (x^{\perp} \cap y^{\perp} \cap p^{\perp})^{\perp},$$

213 we see that $R[x, y] \subseteq U$. Now $R[x, y]$ has at most one vertex in common with each ray in
 214 $\Gamma(p)$ (as extended rays are determined by two points and $R[x, y]$ does not contain p). Since
 215 $|R[x, y]| = q + 1$ and there are precisely $q + 1$ rays of $\Gamma(p)$ in U (as there are $q + 1$ points on
 216 each line in $\Delta(p)$), we conclude that p is collinear to all points of $R[x, y]$ in Δ . \square

217 The proof of Lemma 3.3 yields the following consequence.

218 **Corollary 3.4.** *Let $x, y, z \in X$ be pairwise adjacent with $x \notin R[y, z]$. Then $\pi := (x^{\perp} \cap y^{\perp} \cap z^{\perp})^{\perp}$
 219 is, endowed with all members of \mathcal{L} contained in it, a projective plane. In each of $\Gamma(x), \Gamma(y), \Gamma(z)$, the
 220 point set π minus x, y, z , respectively, represents a line in the corresponding local geometry.*

221 *Proof.* Just like extended rays are determined by any pair of its points, one shows that π is
 222 determined by any triple of its points not contained in a single extended ray. Hence we may think
 223 of two arbitrary extended rays contained in π as, with the notation of the proof of Lemma 3.3,
 224 one containing p and the other containing x . Then the proof of Lemma 3.3 shows that these
 225 two rays intersect in a unique point.

226 The last assertion then also follows from thinking of x, y and z as the vertex p in the proof of
 227 Lemma 3.3. \square

228 An immediate consequence of Corollary 3.4 is the following.

229 **Corollary 3.5.** *Let C be a maximal clique of Γ and $v \in C$. Then C , endowed with the extended rays, is a*
 230 *projective space, say of dimension k which corresponds in the local geometry at v to a maximal singular*
 231 *subspace of dimension $k - 1$.*

232 It follows now by connectivity that the maximal singular subspaces of all local geometries
 233 have the same dimension (since all local geometries we consider admit a point transitive auto-
 234 morphism group). Hence, in order to show Main Result 2.1, it suffices to show the following
 235 proposition.

236 **Proposition 3.6.** *If for each vertex $p \in X$ the local geometry $\Delta(p)$ is a polar space of rank $r \geq 2$ having*
 237 *$q + 1$ points per line, then Δ is a polar space of rank $r + 1$ and, consequently, Γ being the point graph of*
 238 *Δ , it is the point graph of a polar space.*

239 *Proof.* We begin with showing that Δ is a Shult space. Since Δ is a gamma space, we only have
 240 to prove that each line L has at least one point collinear with each point p . This is trivial if
 241 $p \in L$, so assume $p \notin L$. Without loss of generality we may assume for a contradiction, and
 242 by connectivity, that there is no vertex on L adjacent to p in Γ , but there exists a vertex $y \in X$
 243 adjacent to p and adjacent to some point $x \in L$. Since $\Delta(x)$ is a polar space of rank at least 2,
 244 we find a point $z \in \Gamma(x) \cap \Gamma(y)$ not on $R[x, y]$. In $\Delta(y)$, the extended ray $R[y, p]$ represents a
 245 point p^* and, by Corollary 3.4, the set $\pi := (x^\perp \cap y^\perp \cap z^\perp)^\perp$ represents a line L^* . Then there is
 246 a point v^* on L^* collinear to p^* in $\Delta(y)$. This translates in $\Gamma(y)$ to the existence of some vertex
 247 $v \in \pi \setminus \{y\}$ adjacent to p . Since $v \sim p$, all vertices of $R[y, v]$ are adjacent to all those of $R[y, p]$.
 248 Again by Corollary 3.4, the sets $R[y, v]$ and $R[x, z]$ intersect in some point $s \sim p$.

249 If y is adjacent to all vertices of L , then we could have chosen z on L and $p \sim s \in L$.

250 If not, then we can choose z collinear to all points of L ; it follows that s is also collinear to
 251 all points of L . Letting s play the role of y , we are now back to the situation in the previous
 252 paragraph and find a point on L adjacent to p . This shows that Δ is a Shult space.

253 It remains to show that no vertex is adjacent to all other vertices. If some vertex v were adjacent
 254 to all other vertices, then clearly, for each $w \in X \setminus \{v\}$, the local geometry $\Delta(w)$ would be
 255 degenerate. □

256 The parapolar spaces $A_{1,1}(q) \times A_{n,1}(q)$, $n \geq 2$, have maximal singular subspaces which are
 257 lines. This is not true in any other parapolar space which is isomorphic to a point residual
 258 of one of the parapolar spaces mentioned in the hypotheses of Main Result 2.2. So we may
 259 assume that either all local geometries are isomorphic to $A_{1,1}(q) \times A_{n,1}(q)$, $n \geq 2$, or none are.
 260 In the present section, we continue with the latter assumption, delaying the proof of the former
 261 to the next section.

262 **Proposition 3.7.** *If for each vertex $p \in X$ the local geometry $\Delta(p)$ is a strong parapolar space of*
 263 *uniform symplectic rank $r \geq 3$ having $q + 1$ points per line, then for each pair of points $x, y \in X$ of Δ*
 264 *at distance 2 in Γ , the subgeometry $x^\perp \cap y^\perp$ of Δ is a polar space of rank r .*

265 *Proof.* Let $x, y \in X$ be two vertices of Γ at mutual distance 2 and let $p \in x^\perp \cap y^\perp$ be arbitrary.
 266 Let x^* and y^* be the points of $\Delta(p)$ corresponding to the extended rays $R[p, x]$ and $R[p, y]$,
 267 respectively. Since $\Delta(p)$ is a strong parapolar space of diameter 2 and symplectic rank $r \geq 3$,
 268 the set $x^{*\perp} \cap y^{*\perp}$ defines a polar space $\Delta'(p)$ of rank $r - 1$. It follows that the local structure
 269 of the graph $\Gamma(x) \cap \Gamma(y)$ at p is the q -clique extension of $\Delta'(p)$. Since this holds for every

270 $p \in \Gamma(x) \cap \Gamma(y)$, Proposition 3.6 implies that $\Gamma(x) \cap \Gamma(y)$ is the point graph of a polar space of
 271 rank r . Since the extended rays are the lines of that polar space, the geometry $x^\perp \cap y^\perp$ endowed
 272 with the extended rays is a polar space of rank r . \square

273 **Remark 3.8.** In the previous proposition, we may weaken the assumptions to the local geome-
 274 tries having symplectic rank *at least* $r \geq 3$ (with the same proof). However, since in all our
 275 applications, the rank is constant, we limit ourselves to this case. The same remark applies to
 276 the next proposition.

277 **Proposition 3.9.** *If for each vertex $p \in X$ the local geometry $\Delta(p)$ is always a strong parapolar space*
 278 *of uniform symplectic rank $r \geq 3$ having $q + 1$ points per line, then the geometry Δ is a parapolar space*
 279 *of symplectic rank $r + 1$. Also, the local geometry in Γ at the point $p \in X$ is precisely the point residual*
 280 *at p in Δ .*

281 *Proof.* By the definition of parapolar spaces given in Section 2.2, we have to show that

- 282 (i) Δ is a connected gamma space. This is true by Lemma 3.3 (and the assumption that Γ is
 283 connected);
- 284 (ii) for each pair of distinct non-collinear points x, y , the geometry induced on $x^\perp \cap y^\perp$ is either
 285 empty, a single point or a polar space. This is true by Proposition 3.7.
- 286 (iii) For each line L , the set L^\perp contains a pair of non-collinear points. This follows from the well-
 287 definedness of the extended ray $R[x, y]$ in $\Gamma(x)$, where $x, y \in L, x \neq y$.

288 The last assertion is immediate. This completes the proof. \square

289 We are now ready to prove part of Main Result 2.2. We reformulate.

290 **Theorem 3.10.** *Let Γ be a connected graph locally isomorphic to the disjoint union of $\Gamma(D_{n,n}(q))$,*
 291 *$4 \leq n \leq 9$, q ranging over all prime powers, $\Gamma(E_{6,1}(q))$, q again ranging over all prime powers, and*
 292 *$\Gamma(E_{7,7}(q))$, q once again ranging over all prime powers. Then all local geometries of Γ are mutually*
 293 *isomorphic and Γ is isomorphic to either $\Gamma(D_{n,n}(q))$, $\Gamma(E_{6,1}(q))$, or $\Gamma(E_{7,7}(q))$, for some prime power*
 294 *q .*

295 *Proof.* We know by Proposition 3.9 that $\Delta = (X, \mathcal{L})$ is a parapolar space of symplectic rank
 296 at least 4. Now consider two adjacent vertices $x, y \in X$ of Γ . Then, by Corollary 3.5, the
 297 dimensions of the maximal singular subspaces in the local geometries $\Delta(x)$ and $\Delta(y)$, through
 298 the points corresponding to the extended ray $R[x, y]$, are the same. However, for the given
 299 parapolar space, these (well-known) dimensions (for each point) are the following:

| | | |
|--------------|--|---------|
| $A_{4,2}(q)$ | | 2 and 3 |
| $A_{5,2}(q)$ | | 2 and 4 |
| $A_{6,2}(q)$ | | 2 and 5 |
| $A_{7,2}(q)$ | | 2 and 6 |
| $A_{8,2}(q)$ | | 2 and 7 |
| $D_{5,5}(q)$ | | 3 and 4 |
| $E_{6,1}(q)$ | | 4 and 5 |

300 Hence all local geometries are isomorphic. If these local geometries, which are the point resid-
301 uals, are of type $A_{n,2}$, $4 \leq n \leq 8$, then by Lemma 4.6 of [12] (see also Lemma 5.3 of [14]),
302 Δ is isomorphic to $D_{n+1,n+1}(q)$. If these local geometries are isomorphic to $D_{5,5}(q)$, then by
303 Lemma 5.1 of [14], Δ is isomorphic to $E_{6,1}(q)$. Finally, if these local geometries are isomorphic
304 to $E_{6,1}(q)$, then by Lemma 5.5 of [14], Δ is isomorphic to $E_{7,7}(q)$.
305 Since the point graph of Δ is Γ , the proof is complete. \square

306 4 The case of symplectic rank 2 for the local geometry

307 In this section, we tackle the remaining case of Main Result 2.2: We assume all local geometries
308 of Γ are parapolar spaces isomorphic to $A_{1,1}(q) \times A_{n,1}(q)$, $n \geq 2$, for some (non-constant) prime
309 power q and some (non-constant) natural number n . The same arguments as in the previous
310 section show that q and n are in fact constants. We define Δ in the same way as before, and we
311 first show that in Δ , for every pair of points x, y at mutual distance 2, the geometry induced on
312 $x^\perp \cap y^\perp$ by the extended rays is a generalised quadrangle isomorphic to a $(q+1) \times (q+1)$ -
313 grid. Where we previously could use Proposition 3.6 to prove that this geometry is a polar
314 space, this fails now as it has rank 2. However, we propose an alternative argument in this
315 specific case.

316 **Lemma 4.1.** *For every pair of points x, y of Δ at mutual distance 2, the geometry induced on $x^\perp \cap y^\perp$
317 by the extended rays is a $(q+1) \times (q+1)$ -grid, where q is the size of any ray.*

318 *Proof.* Let $x \sim p \sim y$. In $\Gamma(p)$ we find vertices v and w such that $R[p, x] \sim R[p, v] \sim R[p, y] \sim$
319 $R[p, w] \sim R[p, x]$. Moreover, we may assume that the planes $\alpha_1 := (x^\perp \cap p^\perp \cap v^\perp)^\perp$ and
320 $\beta_1 = (y^\perp \cap p^\perp \cap w^\perp)^\perp$ correspond to maximal singular subspaces (hence lines) of $\Delta(p)$.

321 In $\Gamma(x)$, the extended rays $R[x, w]$ and $R[x, v]$, which correspond to points of $\Delta(x)$ at mutual
322 distance 2, are adjacent to a unique common ray $R[x, r]$. Note that the set $U_1 := x^\perp \cap r^\perp \cap v^\perp$,
323 endowed with the extended rays, is an $(n+1)$ -dimensional projective space.

324 Likewise, in $\Gamma(y)$, there is a vertex s such that $R[y, v] \sim R[y, s] \sim R[y, w]$. The set $\beta_2 :=$
325 $y^\perp \cap v^\perp \cap s^\perp$, endowed with the extended rays, is a projective plane, and $V_1 = y^\perp \cap s^\perp \cap w^\perp$
326 defines an $(n+1)$ -dimensional singular subspace.

327 Now, in $\Delta(v)$, two maximal singular subspaces of distinct dimension intersect in a unique
328 point, hence $U_1 \cap \beta_2 = R[v, t]$, for some $t \in X$. Since β_2 is a plane, we can assume $t \in R[y, s]$.
329 Then $t \in V_1$ and so $t \sim w$. Hence in $x^\perp \cap y^\perp$ we find the quadrangle $p \sim v \sim t \sim w \sim p$.

330 Let z be any vertex on $R[t, v]$. Then there is a unique $(n+1)$ -dimensional singular subspace
331 V_2 of Δ through $R[y, z]$, and it intersects β_1 in a unique extended ray $R[y, z']$. Clearly we can
332 choose $z' \in R[p, w]$ (since β_2 is a projective plane). Likewise, for each vertex $u \in R[t, w]$,
333 the unique $(n+1)$ -dimensional singular subspace through $R[x, u]$ intersects the plane α_1 in
334 a ray $R[x, u']$, with $u' \in R[p, v]$. Moreover, $\alpha_3 := x^\perp \cap z^\perp \cap z'^\perp$ defines a plane and $U_2 :=$
335 $x^\perp \cap u^\perp \cap u'^\perp$ defines an $(n+1)$ -dimensional singular subspace. In $\Delta(x)$, these spaces intersect
336 in a unique point, which implies that the extended rays $R[z, z']$ and $R[u, u']$ intersect in a point.
337 Hence, varying z on $R[t, v]$ and u on $R[t, w]$, we obtain a $(q+1) \times (q+1)$ -grid in $x^\perp \cap y^\perp$.

338 It remains to show that there are no other vertices contained in $x^\perp \cap y^\perp$. Suppose for a con-
339 tradiction that some vertex $a \in X$ not on the above grid is adjacent to both x and y . Since
340 $R[p, v]$ intersects every maximal singular subspace of dimension $n+1$ of Δ through x , we may

341 assume that $a \in U_1 \setminus R[v, t]$. Then the plane $(a^\perp \cap t^\perp \cap v^\perp)^\perp$ is contained in the two distinct
 342 maximal cliques $a^\perp \cap t^\perp \cap v^\perp \cap x^\perp$ and $a^\perp \cap t^\perp \cap v^\perp \cap y^\perp$. This contradicts the local structure
 343 in $\Gamma(a)$. \square

344 Now the proof of Proposition 3.9 can be repeated verbatim, and we have the following extension
 345 of Theorem 3.10.

346 **Theorem 4.2.** *Let Γ be a connected graph locally isomorphic to the disjoint union of $\Gamma(A_{n,2}(q))$, $n \geq 4$,
 347 q ranging over all prime powers, $\Gamma(D_{n,n}(q))$, $4 \leq n \leq 9$, q ranging over all prime powers, $\Gamma(E_{6,1}(q))$,
 348 q again ranging over all prime powers, and $\Gamma(E_{7,7}(q))$, q once again ranging over all prime powers.
 349 Then all local geometries of Γ are mutually isomorphic and Γ is isomorphic to either $\Gamma(A_{n,2}(q))$, $n \geq 4$,
 350 $\Gamma(D_{n,n}(q))$, $4 \leq n \leq 9$, $\Gamma(E_{6,1}(q))$, or $\Gamma(E_{7,7}(q))$, for some prime power q .*

351 *Proof.* In view of Theorem 3.10, we may assume that at some vertex the local geometry is
 352 $A_{1,1}(q) \times A_{n,1}(q)$, for some $n \geq 2$ and some prime power q . Lemma 3.2 implies that the local
 353 geometry at each vertex is defined over \mathbb{F}_q . Moreover, since the maximal singular subspaces
 354 of $A_{1,1}(q) \times A_{n,1}(q)$ have dimensions 1 and n , the argument in the proof of Theorem 3.10 using
 355 Corollary 3.5 shows that the local geometry at each vertex is $A_{1,1}(q) \times A_{n,1}(q)$.

356 Hence all point residuals of the parapolar space Δ are isomorphic to $A_{1,1}(q) \times A_{n,1}(q)$. Then
 357 Lemma 5.4 of [14] implies that Δ is isomorphic to $A_{n+2,2}(q)$. Since the point graph of Δ is Γ , the
 358 proof is complete. \square

359 **Remark 4.3.** One can merge Main Results 2.1 and 2.2 by assuming that each residual geometry
 360 is either a polar space of rank at least 3, or a parapolar space as in Main Result 2.2. The con-
 361 clusion is then that Γ is the point graph of either a polar space, or one of the geometries in the
 362 conclusion of Main Result 2.2. The reason is that polar spaces only have one type of maximal
 363 singular subspaces, and then with the help of Corollary 3.5, one concludes that in all points
 364 the residuals are either polar spaces—and we are in the case of Main Result 2.1— or proper
 365 parapolar spaces—and we are in the case of Main Result 2.2.

366 **Remark 4.4.** In Main Result 2.2 we can slightly relax the restriction on the diameter of $\Gamma(D_{n,n}(q))$
 367 to also include the case $n = 10$. Indeed, in this case the proof Theorem 3.10 implies that Γ is
 368 either $\Gamma(D_{10,10}(q))$, or a proper quotient of $\Gamma(D_{10,10}(q))$ with respect to a nontrivial automor-
 369 phism group G . However, suppose we are in the latter case and let $g \in G$ be nontrivial. In
 370 order to preserve the local structure, g must map every vertex to a vertex at distance 5 (see
 371 Lemma A.5 of [14]), which is an opposite vertex in the corresponding building. This contra-
 372 dicts Theorem 1.2 of [15]. Hence no proper quotients occur.

373 Without proof we mention that more elaborate arguments also prove that $\Gamma(D_{n,n}(q))$, $11 \leq n \leq$
 374 17 , does not admit a quotient with the same local structure.

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