

# Applying algebraic graph theory to some problems in incidence geometry

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(includes joint work with Valentina Pepe and Leo Storme)

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## Outline

- Problems in incidence geometry and link with graph theory
- General (algebraic) graph theory
- Some problems in dual polar graphs attacked with algebraic combinatorics

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- Objects are often referred to as *points, lines, planes, ...*
- Plenty of examples: projective spaces, polar spaces, generalized polygons, unitals, inversive planes, ...
- Many of these incidence structures are *spherical buildings* (Tits) (related to Coxeter groups)

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### Example of problem in $\text{PG}(n, q)$

A *partial spread of lines*: a subset of the 2-spaces in  $P_2$ , all pairwise intersecting trivially (i.e. not incident with a common 1-space).  
What is the maximum size for partial spreads of lines?

## Constructing classical polar spaces

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## Axiomatization

- Axioms for polar spaces exist.
- If rank is  $\geq 3$ : finite polar space must be classical (Tits)

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## Graphs

A *graph*  $\Gamma$  consists of:

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### Cliques and cocliques in graphs

- **Clique**: subset of vertices, all mutually adjacent.
- **Coclique**: subset of vertices, no two adjacent.

We can now translate some of our problems.

## Projective spaces

Grassmann graph  $J_q(n+1, 2)$  in  $V(n+1, q)$ :

- 2-spaces as vertices
- $x$  and  $y$  are adjacent if  $\dim(x \cap y) = 1$ .

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Finding partial spreads of lines in  $\text{PG}(n, q)$   
 = finding cliques in  $J_q(n+1, 2)$ .

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Finding partial ovoids in polar space = finding cliques of polar graph.

Geometries  $\implies$  Nice graphs for graph theory people!  
 Graph theory  $\implies$  Solutions for problems of geometry people!

## Association schemes

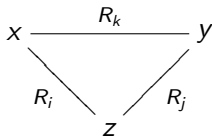
$(\Omega, \{R_0, \dots, R_D\})$  is an association scheme if:

- $\{R_0, \dots, R_D\}$  partitions  $\Omega \times \Omega$ ,
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- $R_0$  is identity relation,
- $(\omega_1, \omega_2) \in R_i \iff (\omega_2, \omega_1) \in R_i$ ,
- there are *intersection numbers*  $p_{ij}^k$ :  
if  $(x, y) \in R_k$ , the number of elements  $z$  in  $\Omega$   
for which  $(x, z) \in R_i$  and  $(z, y) \in R_j$  is  $p_{ij}^k$ .



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- We define  $R_i$  as  $\{(x, y) \in \Omega \times \Omega \mid d(x, y) = i\}$ .

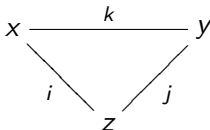
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### Distance-regular graphs

A graph  $\Gamma = (\Omega, E)$  is *distance-regular* if  $(\Omega, \{R_0, \dots, R_d\})$  is association scheme.

So number of  $z$  with  $d(x, z) = i, d(y, z) = j$  only depends on  $i, j, k$ .



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- In particular: distance-regular graphs are regular!

Consider distance-regular graph  $\Gamma$  with vertex set  $\Omega$  and diameter  $d$ :

- Define  $(|\Omega| \times |\Omega|)$ -matrices  $A_0, \dots, A_d$ :

$$(A_i)_{x,y} = \begin{cases} 1 & \text{if } d(x,y) = i \\ 0 & \text{if } d(x,y) \neq i \end{cases} .$$

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- Eigenvalues of  $\Gamma$* : the  $d + 1$  eigenvalues of  $A_1$ .
- $\mathbb{R}^\Omega$  decomposes orthogonally into  $d + 1$  real eigenspaces of  $A_1$ :

$$\mathbb{R}^\Omega = V_0 \perp V_1 \perp \dots \perp V_d.$$

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- These  $V_j$  are in fact eigenspaces for all  $A_i$ !
- Orthogonal projection  $E_j : \mathbb{R}^\Omega \rightarrow V_j$   
can be written as linear combination of  $A_0, \dots, A_d$ . (these projections are *minimal idempotents*)

## Characteristic vectors

For any subset of vertices  $S$ ,

the *characteristic vector*  $\chi_S \in \mathbb{R}^\Omega$  is  $(0, 1, 0, 1, 1, \dots)^T$

with  $(\chi_S)_\omega = 1$  if  $\omega \in S$  and  $(\chi_S)_\omega = 0$  if  $\omega \notin S$ .

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## Linear programming bounds (Delsarte)

- Any minimal idempotent  $E_j$  is positive semidefinite:  
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- Rewriting  $E_j$  as  $\lambda_0^* A_0 + \dots + \lambda_d^* A_d$  in  $(\chi_S)^T E_j \chi_S$  can thus yield powerful information on subset  $S$ .

## Metric and cometric schemes

- Association schemes  $(\Omega, \{R_0, \dots, R_d\})$  with  $R_i$   $i$ -distance relation of distance-regular graph are *metric* or *P-polynomial*.
- Dually, if the minimal idempotents  $E_0, \dots, E_d$  can be ordered in a *nice way*, we call it *cometric* or *Q-polynomial*.

## Definition

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### Dual polar graph from classical polar space

- Vertices: isotropic  $d$ -spaces (or maximals)
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### Distance-regularity of dual polar graph

- Geometric interpretation of distance between vertices:

$$d(x, y) = i \iff \dim(x, y) = d - i.$$

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- Dual polar graph is distance-regular with diameter  $d$ !

## Definition

Size:  $(q^e + 1) \dots (q^{d-1} \cdot q^e + 1)$ ,

Valency:  $q^e(q^d - 1)/(q - 1)$ ,

with  $q$  a prime power and  $e$  depending on type.

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## Types of dual polar graphs

			$e$
hyperbolic	$Q^+(2d - 1, q)$	$D_d(q)$	0
unitary	$H(2d - 1, q^2)$	${}^2A_{2d-1}(q)$	1/2
parabolic	$Q(2d, q)$	$B_d(q)$	1
symplectic	$W(2d - 1, q)$	$C_d(q)$	1
unitary	$H(2d, q^2)$	${}^2A_{2d}(q)$	3/2
elliptic	$Q^-(2d + 1, q)$	${}^2D_{d+1}(q)$	2

(Watch out for confusion between  $q$  and  $q^2$  in unitary case...)

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### Graph-theoretic approach

A partial spread is a set of vertices in the dual polar graph, all at maximal distance  $d$  from each other!

## Applying linear programming bound

- If  $S$  is partial spread, then  $\chi_S A_0 \chi_S = |S|$ ,  $\chi_S A_d \chi_S = |S|(|S| - 1)$  and  $\chi_S A_i \chi_S = 0, \forall i \in \{1, \dots, d - 1\}$ .

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- Dual polar graph is *regular near  $2d$ -gon*, so

$$M = A_0 - \frac{A_1}{q^e} + \frac{A_2}{q^{2e}} - \dots + \frac{(-1)^d A_d}{q^{de}}$$

is minimal idempotent up to positive scalar  
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- If  $d$  is odd  $\implies |S| \leq q^{de} + 1$ .
- This beats spread bound  $q^{d-1} \cdot q^e + 1$  if  $e \in \{0, \frac{1}{2}\}$ , not if  $e \in \{1, \frac{3}{2}, 2\}$ .

Remember: partial spreads consist of vertices of dual polar graph, all at maximal distance  $d$ !

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- For  $d = 3$ :  $q^d + 1$  is the maximum size (De Beule-Metsch, 2007)

Remember: partial spreads consist of vertices of dual polar graph, all at maximal distance  $d$ !

Partial spreads for  $e = 1/2$  (the unitary dual polar graph  ${}^2A_{2d-1}(q)$ )

- Partial spreads in  ${}^2A_{2d-1}(q)$  have size less than  $(q^2)^{d-1} \cdot q + 1$  (so no spreads) (Thas, 1990)
- Partial spreads of size  $q^d + 1$  always exist in  ${}^2A_{2d-1}(q)$  (Aguglia-Cossidente-Ebert, 2001)
- For  $d = 3$ :  $q^d + 1$  is the maximum size (De Beule-Metsch, 2007)
- For all odd  $d$ :  $q^d + 1$  is the maximum size (linear programming, 2009)

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- This can be proved by elementary means using *variance trick*.
- Keeping  $|S|$  variable in that proof actually yields  $|S| \leq q^d + 1$  as well!

We now treat the converse problem.  
(joint work with Valentina Pepe and Leo Storme)  
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- An EKR-family in a dual polar graph is a family of maximals (isotropic  $d$ -spaces) all pairwise intersecting non-trivially (so in at least 1-space).

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## Erdős-Ko-Rado-problem in dual polar graphs

- An EKR-family in a dual polar graph is a family of maximals (isotropic  $d$ -spaces) all pairwise intersecting non-trivially (so in at least 1-space).
- How big can they be?
- Is taking all maximals through fixed 1-space (unique?) optimal construction?

Remember about dual polar graph:

- vertices: isotropic  $d$ -spaces (or maximals) w.r.t form on vector space,
- $x$  and  $y$  are at maximal distance  $d$  iff they intersect trivially.

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### Relevant works

- Brouwer-Godsil-Koolen-Martin: Width and dual width of subsets in polynomial association schemes (2004)
- Tanaka: Classification of subsets with minimal width and dual width in Grassmann, bilinear forms and dual polar graphs (2007)

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In a regular graph  $\Gamma = (\Omega, E)$  with valency  $k$  and minimal eigenvalue  $\lambda$ , a coclique  $S$  satisfies:

$$|S| \leq \frac{|\Omega|}{1 - k/\lambda}.$$

If equality holds:  $\chi_S - \frac{|S|}{|\Omega|}\chi_\Omega$  in eigenspace  $\lambda$ .

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So we must study eigenvalues and eigenspaces of  $A_d$ !

## Eigenspaces of dual polar graph $\Gamma$ and $A_d$

- Define  $V_0 = \langle \chi_\Omega \rangle$  and construct  $V_i$  ( $1 \leq i \leq d$ ) such that  $V_0 \perp \dots \perp V_i$  is image of incidence matrix from  $i$ -spaces to  $d$ -spaces.

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- These  $V_i$  are also eigenspaces for  $A_d, \dots$  or subspaces of eigenspaces!

## What happens in most dual polar graphs for EKR-families $S$

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- Tanaka's results (2007): equality  $\iff$   
 $S$  is all maximals through fixed isotropic 1-space

We have to consider the different types of dual polar graphs separately!

			$e$
hyperbolic	$Q^+(2d - 1, q)$	$D_d(q)$	0
unitary	$H(2d - 1, q^2)$	${}^2A_{2d-1}(q)$	1/2
parabolic	$Q(2d, q)$	$B_d(q)$	1
symplectic	$W(2d - 1, q)$	$C_d(q)$	1
unitary	$H(2d, q^2)$	${}^2A_{2d}(q)$	3/2
elliptic	$Q^-(2d + 1, q)$	${}^2D_{d+1}(q)$	2

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- Solution: work in each bipartite half (half dual polar graph) and slightly adjust Tanaka's arguments to obtain classification.

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- Answer: equality iff  $S$  is all maximals through 1-space, half of an embedded  $D_d(q)$ , or extra construction for  $d = 3$ .

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- Number of vertices through fixed 1-space:  $\frac{|\Omega|}{q^{2d-1}+1}$ .
- For  $d=3$ , maximum size by taking one vertex and neighbours:  
 $1 + q(q^4 + q^2 + 1)$ :

$$\begin{array}{lll} \text{all through 1-space} & < \text{maximum size} & < \text{eigenvalue bound} \\ (q+1)(q^3+1) & < 1 + q(q^4 + q^2 + 1) & < (q+1)(q^5+1). \end{array}$$

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(so all vertices at maximal distance  $d$ )  
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- Maximum size for partial spreads in  ${}^2A_{2d-1}(q)$  for even  $d$ ?  
(so all vertices at maximal distance  $d$ )  
(answer is at least  $q^d + 1$ )
- Maximum size for EKR-families in  ${}^2A_{2d-1}(q)$  for odd  $d \geq 5$ ?  
(so no 2 vertices at maximal distance  $d$ )

# Thank you for your attention!

(Slides (and more) on <http://cage.ugent.be/~fvanhove>)