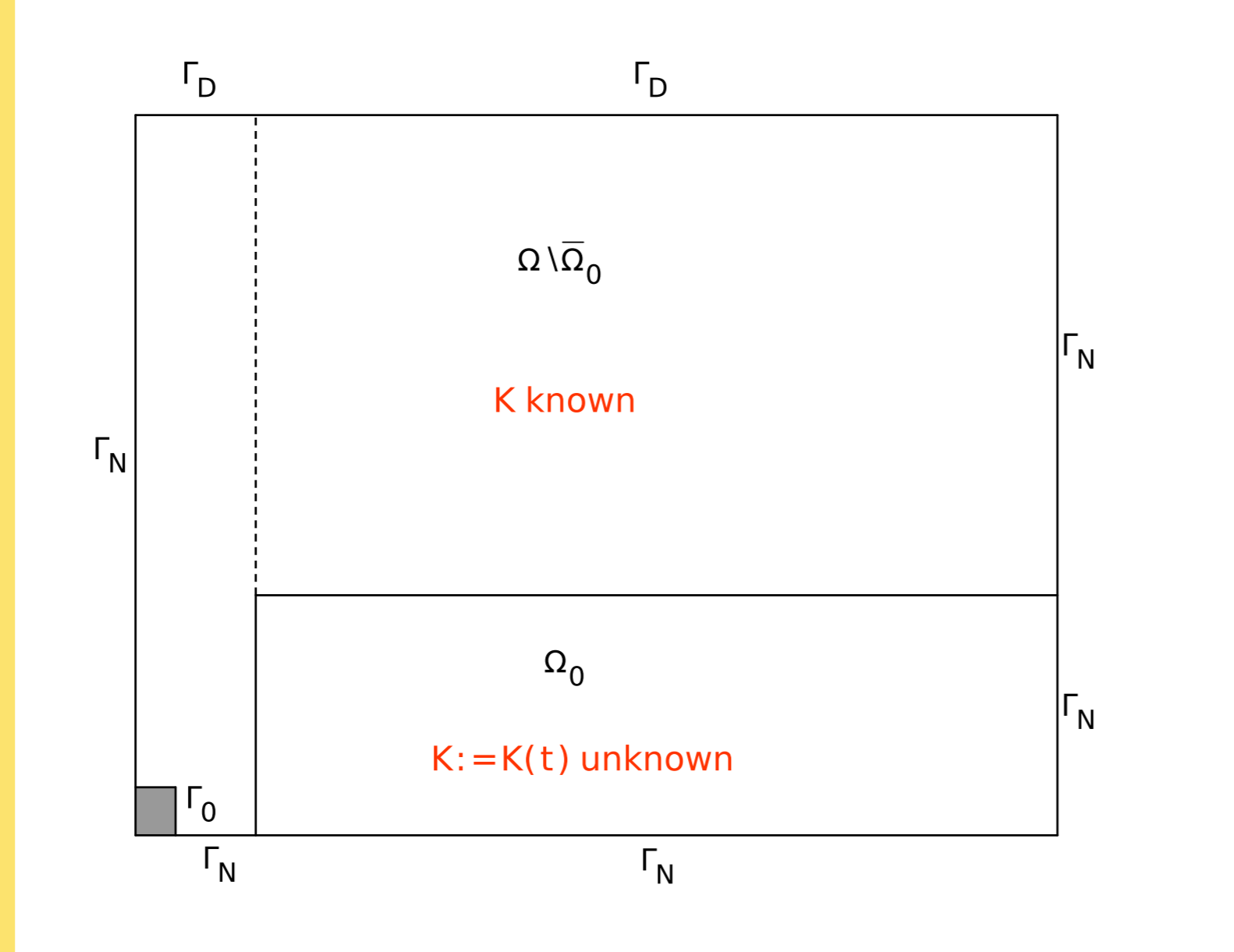


## Application

- ▷ Spontaneous potential well-logging is an important technique to detect parameters (e.g. resistivity, diffusivity) of the formation in petroleum exploitation;
- ▷ The resistivity can depend on temperature and humidity in some geological formations. This makes the problem of the resistivity identification time-dependent.



## Mathematical model (IBVP)

Find  $(K, u)$  such that ( $T > 0$  fixed)

$$\begin{aligned} \partial_t u - \nabla \cdot (K \nabla u) &= f(u) && \text{in } (0, T) \times \Omega; \\ u &= g^D && \text{in } (0, T) \times \Gamma_D; \\ -K \nabla u \cdot \nu &= g^N && \text{in } (0, T) \times \Gamma_N; \\ u(0) &= u_0 && \text{in } \Omega; \end{aligned}$$

with the following conditions on  $\Gamma_0$

$$\begin{cases} \int_{\Gamma_0} -K \nabla u \cdot \nu = h(t) & \text{in } (0, T); \\ u = U(t) & \text{on } (0, T) \times \Gamma_0. \end{cases}$$

## Solution method: time discretization

The time discretization is based on Backward Euler's method. Divide the time interval  $[0, T]$  into  $n \in \mathbb{N}$  equidistant subintervals  $(t_{i-1}, t_i)$  for  $t_i = i\tau$ , where  $\tau = T/n$  and introduce the following notation for any function  $z$

$$z_i = z(t_i), \quad \delta z_i = \frac{z_i - z_{i-1}}{\tau}.$$

**First solution method:** determine a solution of

$$\begin{aligned} \delta u_i - \nabla \cdot (K_i \nabla u_i) &= f(u_{i-1}) && \text{in } \Omega; \\ u_i &= 0 && \text{on } \Gamma_D; \\ -K_i \nabla u_i \cdot \nu &= 0 && \text{on } \Gamma_N; \\ \int_{\Gamma_0} -K_i \nabla u_i \cdot \nu &= h_i && \end{aligned}$$

for a given  $K_i, i = 1, \dots, n$ . Search  $K_i$  such that  $u_i|_{\Gamma_0} = U_i$ .

**Second solution method:** solve

$$\begin{aligned} \delta u_i - \nabla \cdot (K_i \nabla u_i) &= f(u_{i-1}) && \text{in } \Omega; \\ u_i &= 0 && \text{on } \Gamma_D; \\ -K_i \nabla u_i \cdot \nu &= 0 && \text{on } \Gamma_N; \\ u_i &= U_i && \text{on } \Gamma_0 \end{aligned}$$

for a given  $K_i, i = 1, \dots, n$ . Search  $K_i$  such that  $\int_{\Gamma_0} -K_i \nabla u_i \cdot \nu = h_i$ .

## First result

Both solution methods give the existence of  $(K_i, u_i) \in \mathbb{R}_+ \times V$  for  $\tau < \tau_0$ , with  $V := \{\varphi \in H^1(\Omega); \varphi|_{\Gamma_D} = 0, \varphi|_{\Gamma_0} = \text{const}\}$ .

## Rothe functions

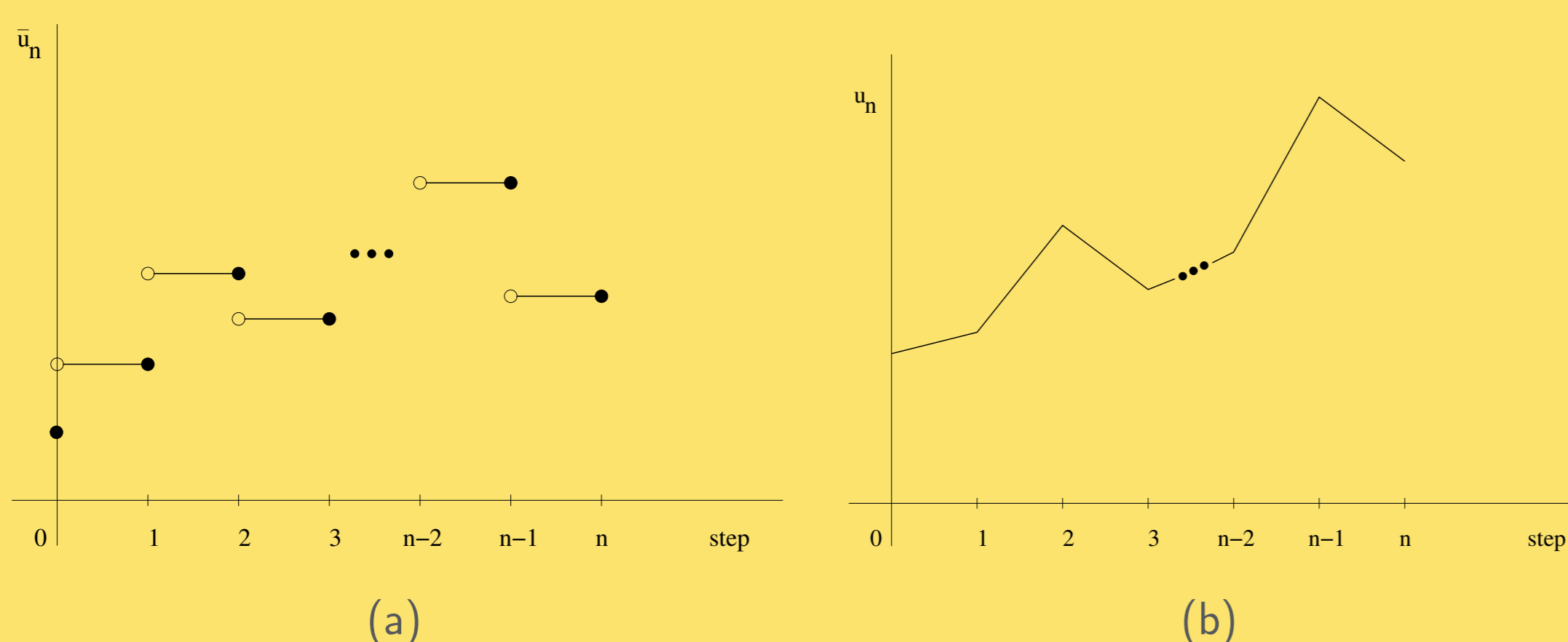


Figure 1: Rothe's piecewise constant function  $\bar{u}_n$  (a) and piecewise linear in time function  $u_n$  (b).

## Variational formulation of IBVP

Find  $(K, u)$  such that

$$\begin{aligned} (\partial_t u, \varphi) + (K \nabla u, \nabla \varphi) + h \varphi|_{\Gamma_0} &= (f(u), \varphi), \quad \varphi \in V; \\ u|_{\Gamma_0} &= U. \end{aligned}$$

## Second result (limit $n \rightarrow \infty$ , i.e. $\tau \rightarrow 0$ )

There exist a weak solution of the IBVP.

## Numerical experiment

▷  $\Omega := (-\frac{1}{2}, 1) \times (-1, 1)$ ,  $\Omega_0 := (-\frac{1}{2}, 0) \times (-1, 1)$ ,  $T = 1$ ;

▷  $\Gamma_0: x = -\frac{1}{2}$ ,  $\Gamma_D: x = 1$ ,  $\Gamma_N: y = -1$  and  $y = 1$ ;

▷  $K(t, x, y) := \tilde{k}(t) \mathbf{1}_{\{x < 0\}} + \frac{1}{2}$ ;

▷ The exact solution (for checking purposes):

$$\begin{aligned} K(t, x, y) &:= (1 + \sin(10t)) \mathbf{1}_{\{x < 0\}} + \frac{1}{2}, \\ u(t, x, y) &:= (1 + t) \sin\left(\frac{\pi}{2}(1 - x)\right); \end{aligned}$$

▷ Add noise with magnitude 1% and 5% to the additional condition

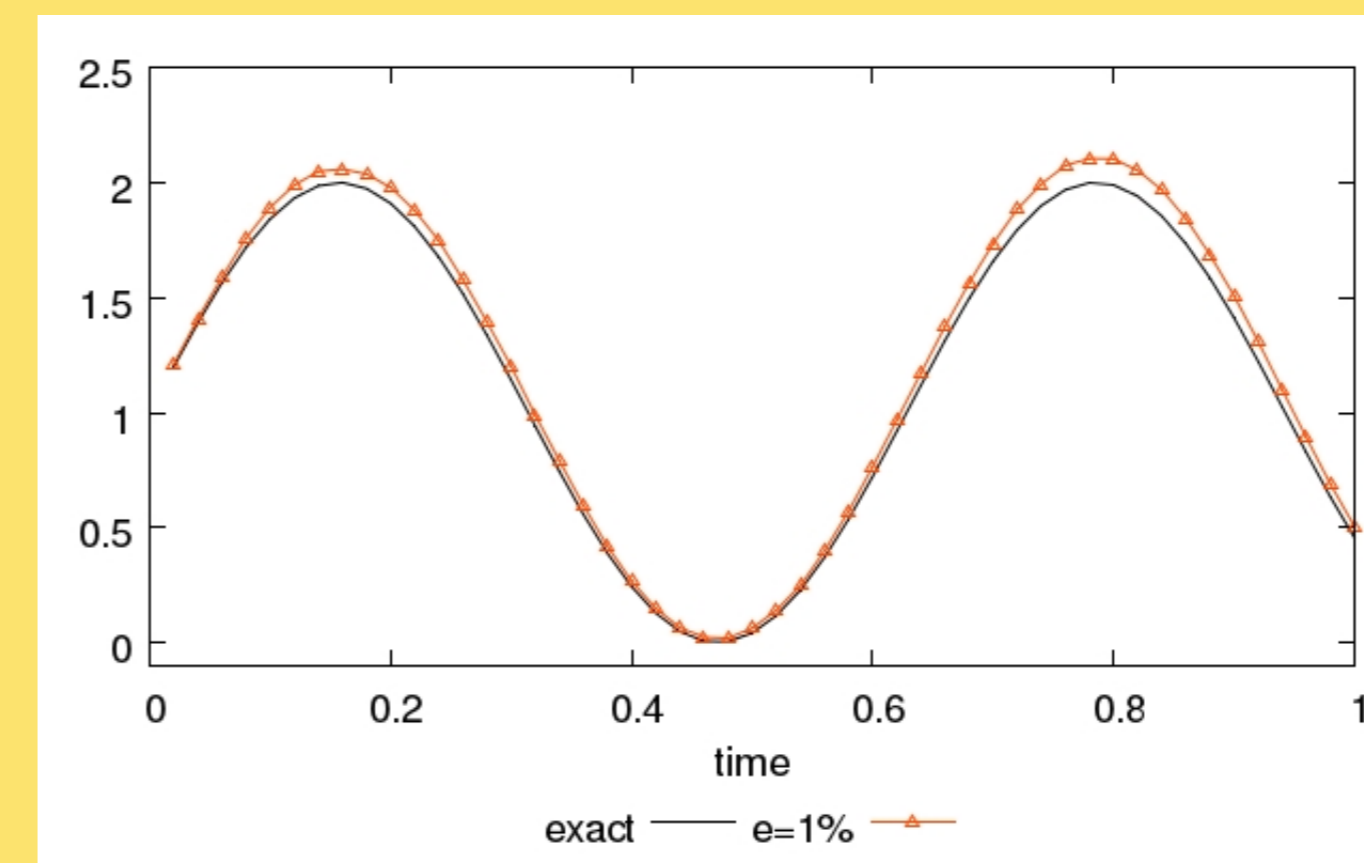
$$h(t) := \frac{\pi}{\sqrt{2}}(1 + t)(1.5 + \sin(10t));$$

▷ The time interval is divided into small intervals of length  $\tau = 0.02$ ;

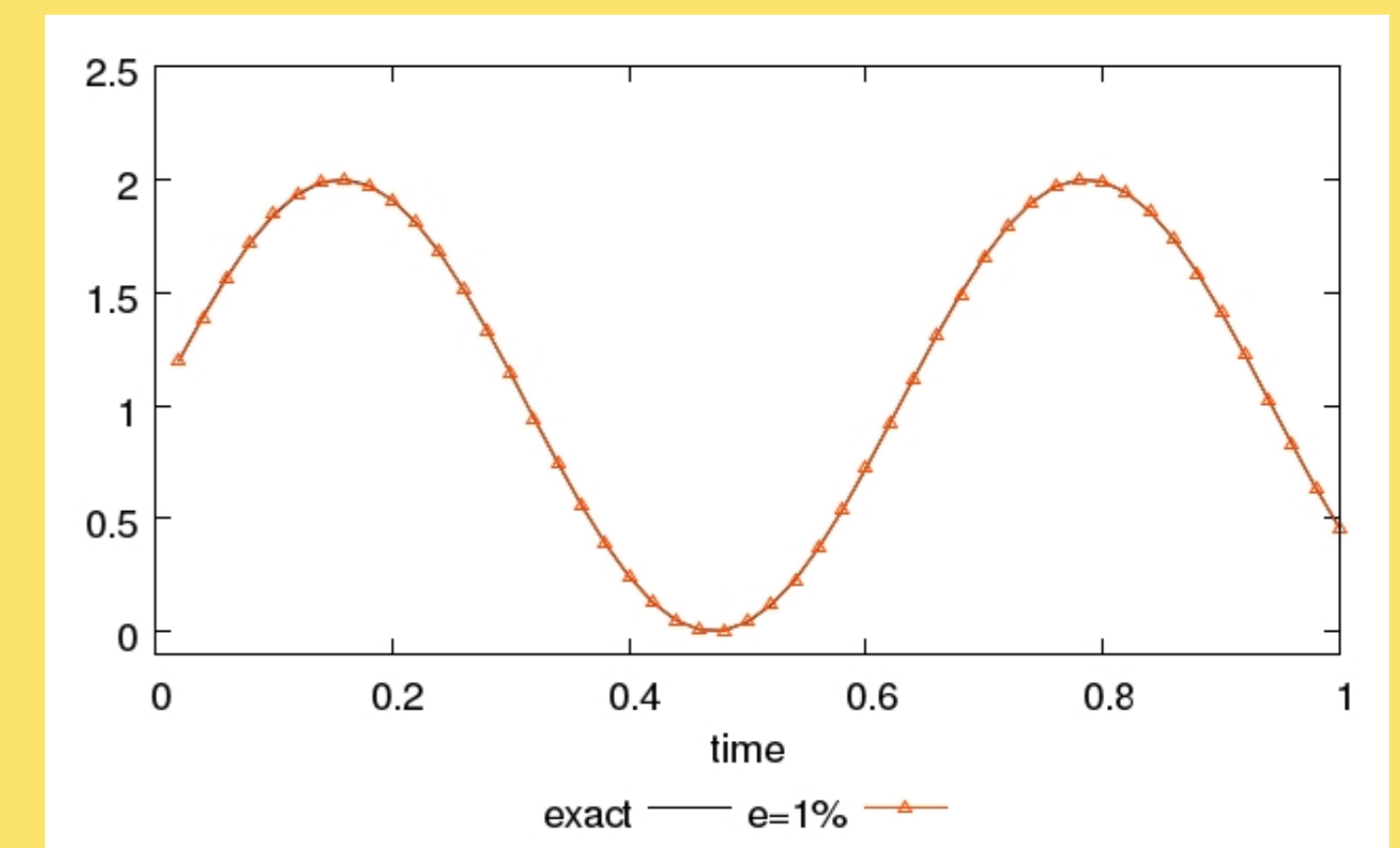
▷ Lagrange P1- and P2-FEM: the space domain is divided into 144528 triangles;

▷ Recovery of  $\tilde{k}(t)$ : on each time-step  $t_i, i = 1, \dots, 50$ , minimize the functional (use the nonlinear conjugate gradient method)

$$J(\tilde{k}_i) := \left( \int_{\Gamma_0} (\tilde{k}_i + 0.5) \nabla u_i \cdot \nu - h(t_i) \right)^2.$$

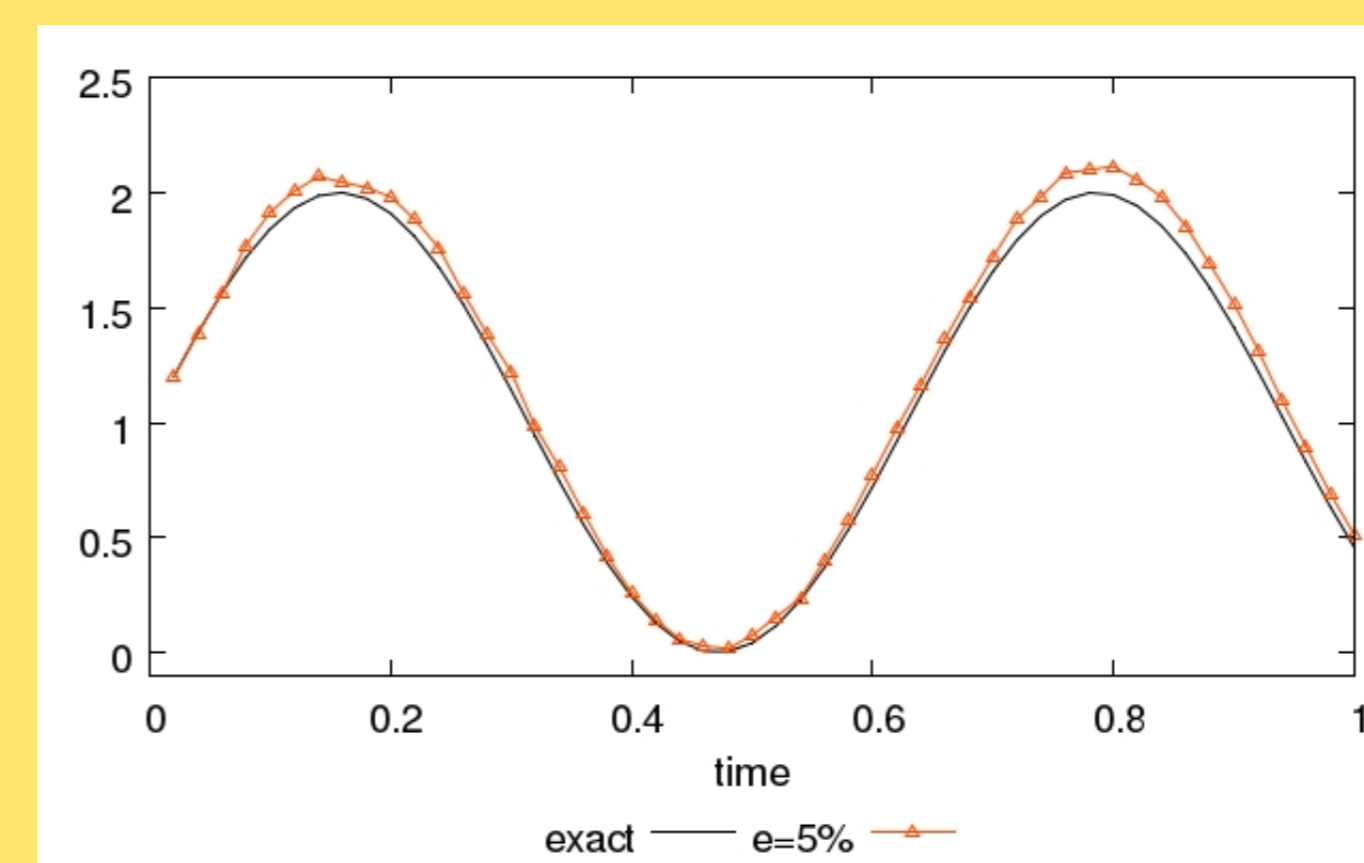


(a)

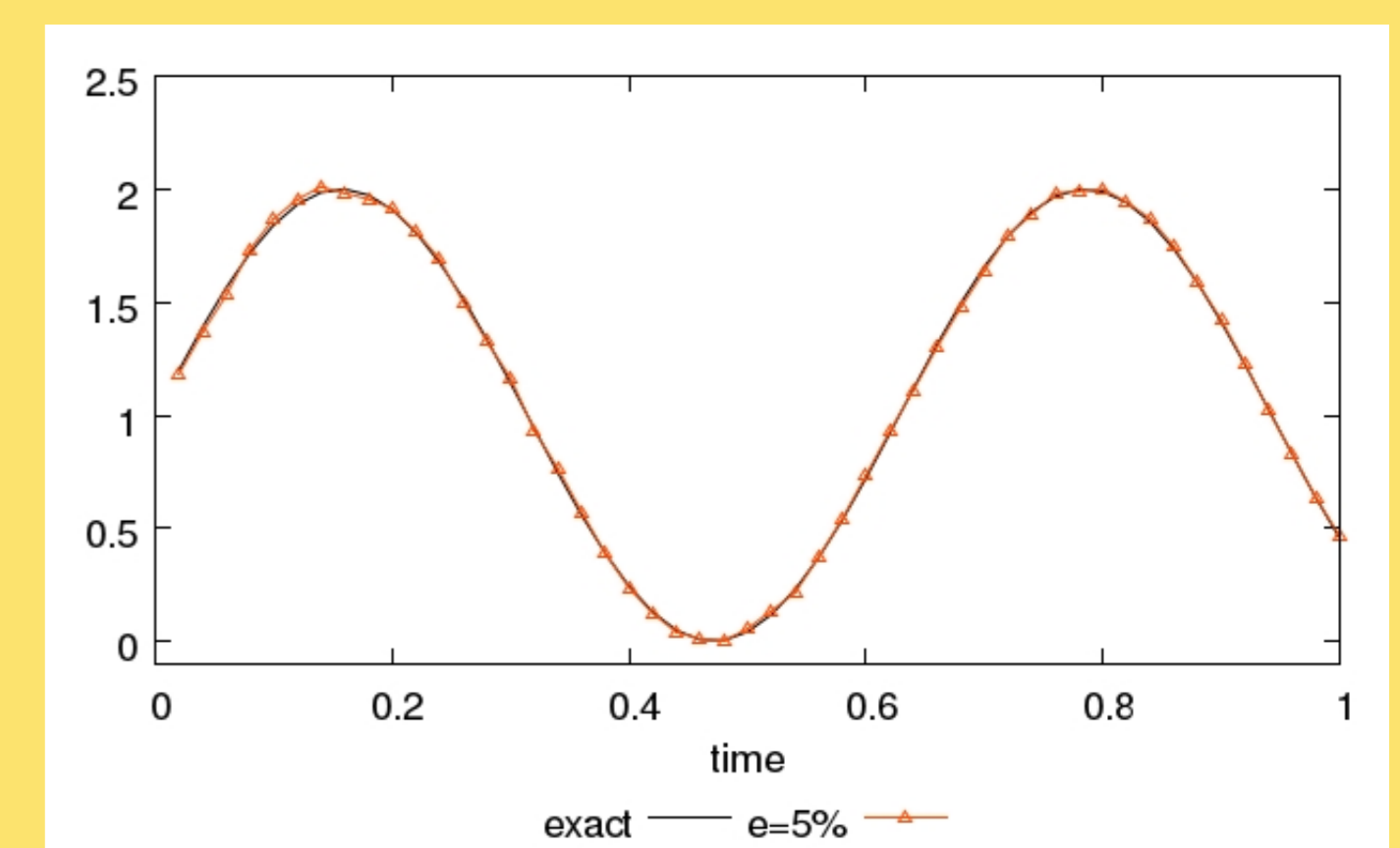


(b)

Figure 2: Numerical value of  $\tilde{k}_i$  using the P1-FEM (a) and P2-FEM (b) with noise  $e = 1\%$ ;  $i = 1, \dots, 50$ .



(a)



(b)

Figure 3: Numerical value of  $\tilde{k}_i$  using the P1-FEM (a) and P2-FEM (b) with noise  $e = 5\%$ ;  $i = 1, \dots, 50$ .

## Further research

- ▷ Uniqueness of the solution?
- ▷ Non-linear differential operator: Richardson.

## Acknowledgement

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